Parallel Lives: Why Quantum Mechanics is a Local Realistic Theory After All

Gilles Brassard and Paul Raymond-Robichaud¹

Département d'informatique et de recherche opérationnelle Université de Montréal

24 April 2015, New Directions in the Foundations of Physics

¹All the ideas presented here originate with Paul Raymond-Robichaud. Gilles Brassard is merely the passionate messenger!

Introduction

Intuitive Desiderata

Local States

Local Evolution

Observations in Quantum Mechanics

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

Parallel Lives vs Many Worlds

A Local Realist Formalism

Conclusion

The Meaning and non-Meaning of Bell's Theorem

Conventional Wisdom: The violation of Bell's inequality is incompatible with local realism.

Fact: This is false!

Truth: The violation of Bell's inequality is incompatible with local hidden variable theories. *That's Different!*

What about Quantum Mechanics? Can it be local realistic, Bell's Theorem notwithstanding?

> Yes! It can! It was prophecised by Everett, explained by Frank Tipler to Deutsch, published by Deutsch and Hayden (2000).

Can it be done in a simple way? YES!

Introduction

Intuitive Desiderata

Local States

Local Evolution

Observations in Quantum Mechanics

Parallel Lives vs Many Worlds

A Local Realist Formalism

Conclusion

Desiderata for Local Realism

- Systems should have local physical states.
- Systems should have local evolution.
- The whole should be fully described by its parts.
- Observations of a system should be determined by its physical state.

(ロ) (同) (三) (三) (三) (三) (○) (○)

Desiderata for Local Realism

Warning!

By local realist we do not merely mean that no action at point A can have instantaneous *observable* effects at point B.

We mean no effect whatsoever on the state at point B.

But WAIT!

Didn't John Bell prove in 1964 that this is impossible?!

Not really... He proved that it's impossible by use of local hidden variables.

He also said: What is proved by impossibility proofs is lack of imagination

And Einstein said: Imagination is more important than knowledge

So...Could there be another local-realistic way?

One that requires just a little more imagination!

Digression: Popescu-Rohrlich Nonlocal Boxes

- They violate a Bell inequality (CHSH) maximally.
- CHSH_{PR} = 4; CHSH_{QM} = $2\sqrt{2} \approx 2.83$; CHSH_{Classical} = 2
- So, PR-boxes are even more "nonlocal" than quantum mechanics.
- Yet, they can be given a fully local-realistic explanation!
- This proves that the violation of a Bell inequality is not a proof of nonlocality... Bell's theorem notwhitstanding!

Non-local boxes



Non-Local Boxes

They cannot be used to communicate: They are causal and atemporal

They can be simulated *classically* with probability 75%

They can be simulated quantumly with probability $\cos^2 \frac{\pi}{8} = \frac{2+\sqrt{2}}{4} \approx 85\%$

Fact about PR Boxes

- The correlations entailed by these PR Boxes provide a maximal violation of the CHSH Bell inequality.
- Hence, they cannot be explained by local hidden variables.
- Nevertheless, let's see how to "implement" them locally!
- For the sake of illustration let us take the inputs in {0, 1} but the outputs in {green, red}

(日) (日) (日) (日) (日) (日) (日)

Parallel Lives: A local realistic interpretation of "nonlocal" boxes

Gilles Brassard and Paul Raymond-Robichaud, Université de Montréal



Imaginary World:

Our imaginary world follows the principles of Locality and Realism.

Principle of Locality: No action taken at a point A can have any effect at a point B at a speed faster than light.

Principle of Realism: There is a real world and observations are determined by the state of the real world.

This world has two inhabitants, Alice and Bob, which are each carrying a PR box, introduced by Popescu and Rorhlich.



A PR box has a "0" and a "1" button. Whenever a button is pushed, it instantaneously flashes a red or green light with equal probability. If Allca and Bob both push a button, they will discover when they meet that they have seen different colours precisely when they both have pushed the "1" button. (Note that the PR box does not readile instantaneous communication between Allca and Bob)

Alice and Bob will test the boxes with this protocol:

They travel far apart in their spaceships. Alice and Bob flip coins and push the corresponding button simultaneously.









Once a button is pushed, the box flashes either a green or red light.

The experiment is performed with sufficient simultaneity that Alice's box cannot know the result of Bob's coin flip (hence the input to Bob's box) before it has to flash its own light, and vice versa.

After many experiments, they meet and realize that the boxes work perfectly.











The key idea

In our imaginary world, the Einstein-Popolsky-Rosen argument does not hold because whenever Alice pushes a button and can predict something about Bob, she is really predicting not what is happening simultaneously at Bob's placebut how their various lives will meet in the future.

http://www.iro.umontreal.ca/~brassard/Bell/poster.jpg

This proves that it is wrong to claim that

any world that violates Bell inequalities has to be nonlocal

http://www.iro.umontreal.ca/~brassard/Bell/poster.jpg

Desiderata for Local Realism

- Systems should have local physical states.
- Systems should have local evolution.
- The whole should be fully described by its parts.
- Observations of a system should be determined by its physical state.

(ロ) (同) (三) (三) (三) (三) (○) (○)

Desiderata for Local Realistic Quantum Mechanics

- Systems should have local physical states.
- Systems should have local evolution.
- The whole should be fully described by its parts.
- Observations of a system should be determined by its physical state and be the same as those of quantum mechanics.

(日) (日) (日) (日) (日) (日) (日)

- PR-nonlocal boxes do *not* fulfil this last condition.
- But we can! :-)

Introduction

Intuitive Desiderata

Local States

Local Evolution

Observations in Quantum Mechanics

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

Parallel Lives vs Many Worlds

A Local Realist Formalism

Conclusion

Local States

Complete Description

For any system X, let M^X denote its complete description.



Local States

Separation

The parts come from the whole:

$$M^{A} = \operatorname{tr}_{B}\left(M^{AB}\right)$$

Local States

Merging

If we have a system *A* and a system *B*, it is possible to join them and form a composite system *AB*.

The state of the composite system is **completely** determined by the state of its parts:

$$M^{AB} = M^A \odot M^B$$
.

◆□▶ ◆□▶ ◆□▶ ◆□▶ ● ● ● ●

Even for entangled states! P.S. This is the point of this talk!

Introduction

Intuitive Desiderata

Local States

Local Evolution

Observations in Quantum Mechanics

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

Parallel Lives vs Many Worlds

A Local Realist Formalism

Conclusion

Evolution of Isolated Systems

If we apply an operation U to an isolated system A that was in state M_1^A , the new state of the system M_2^A will be determined only by its previous state and the operation.

$$M_2^A = U\left(M_1^A\right)$$

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

Evolution is a Group Action

$$V\left(U\left(M^{A}\right)\right) = (VU)\left(M^{A}\right)$$
$$I\left(M^{A}\right) = M^{A}$$

Separate Evolution

If we apply U to system A and V to system B, the resulting joint state can be obtained by purely local operations on A and B:

$$(U \otimes V) (M^{AB}) = U (M^{A}) \odot V (M^{B})$$

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

Introduction

Intuitive Desiderata

Local States

Local Evolution

Observations in Quantum Mechanics

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

Parallel Lives vs Many Worlds

A Local Realist Formalism

Conclusion

The axioms must give rise to the same *observations* as those in standard quantum mechanics.

However, these observations are mere individual *perceptions*, which are explained to be unavoidable by the theory itself.

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ のQ@

The Density Matrix

The density matrix encompasses all that is observable about a system.

Observations are determined by the state of the system.

It follows that the density matrix must be a function of the physical state of the system:

$$\rho^{\mathsf{A}} = f\left(\mathsf{M}^{\mathsf{A}}\right) \ .$$

(ロ) (同) (三) (三) (三) (三) (○) (○)

The Density Matrix

$$U\left(f\left(M^{A}\right)\right)=f\left(U\left(M^{A}\right)\right)$$



◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ のQ@

Here, $U(\rho^A) = U\rho^A U^{\dagger}$, but what of $U(M^A)$? This will be defined soon!

The Density Matrix

$$f\left(\mathrm{tr}_{B}\left(M^{AB}\right)\right) = \mathrm{tr}_{B}\left(f\left(M^{AB}\right)\right)$$



Again, $tr_B(\rho^{AB})$ is the usual partial trace in quantum mechanics, whereas $tr_B(M^{AB})$ will be defined soon!

Introduction

Intuitive Desiderata

Local States

Local Evolution

Observations in Quantum Mechanics

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

Parallel Lives vs Many Worlds

A Local Realist Formalism

Conclusion

Parallel Lives vs Many Worlds

The universal wave function cannot be the complete description of a local universe. It merely describes what can be observed.

The universal wave function is but a shadow of the real world!

(日) (日) (日) (日) (日) (日) (日)

Parallel Lives vs Many Worlds

Bell States and Bit flips: A reminder

Two of the four Bell States:

$$ig|\Psi^+ig
angle = rac{1}{\sqrt{2}} \left(ig|10
angle + ig|01
angle
ight) \ ig|\Phi^+ig
angle = rac{1}{\sqrt{2}} \left(ig|11
angle + ig|00
angle
ight)$$

The negation gate:

$$N = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

Parallel Lives vs Many Worlds

According to the Desiderata, all states are separable:

$$|\Psi^+
angle=M^{A}\odot M^{B}$$

By separate evolution:

$$(N \otimes N) |\Psi^+\rangle = N \left(M^A\right) \odot N \left(M^B\right)$$

Since

$$\left|\Psi^{+}
ight
angle=(\mathit{N}\otimes \mathit{N})\left|\Psi^{+}
ight
angle$$

By tracing out B, we conclude

$$M^{A}=N\left(M^{A}\right)$$

However

$$\left|\Phi^{+}\right\rangle = \left(N \otimes I\right)\left|\Psi^{+}\right\rangle = N\left(M^{A}\right) \odot M^{B} = M^{A} \odot M^{B} = \left|\Psi^{+}\right\rangle$$

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

A contradiction!

Introduction

Intuitive Desiderata

Local States

Local Evolution

Observations in Quantum Mechanics

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

Parallel Lives vs Many Worlds

A Local Realist Formalism

Conclusion

States

For a system *A* associated with a Hilbert Space of dimension *n*, its state M^A is formally defined by an *evolution matrix* $[W]^A$, which is an $n \times n$ matrix whose entries are matrices:

$$[W]_{i,j}^{A} \stackrel{\text{def}}{=} W^{\dagger} \Big(|j\rangle \langle i| \otimes I^{\overline{A}} \Big) W$$

for some unitary W on the global state, which corresponds to all that happened to the universe since the beginning of time.

(日) (日) (日) (日) (日) (日) (日)

If we have a system A in state $\begin{bmatrix} W \end{bmatrix}^A$ on which we apply a unitary operation U, the system evolves to

$$U[W]^A$$

defined as

$$\left(U\left[W\right]^{A}\right)_{i,j} \stackrel{\text{def}}{=} \sum_{m,n} U_{i,m} \left[W\right]_{m,n}^{A} U_{n,j}^{\dagger}$$

Theorem

$$U[W]^{A} = \left[\left(U \otimes V \right) W \right]^{A}$$

for any unitary V acting on \overline{A}

Local Evolution Proof

$\left(U\left[W\right]^{A}\right)_{i,j} = \sum_{m,n} U_{i,m} [W]_{m,n}^{A} U_{n,j}^{\dagger}$ $\mathcal{L} = \sum \langle i | U | m angle \left(\mathcal{W}^{\dagger} ig(| n angle \! \langle m | \otimes I^{\overline{A}} ig) \mathcal{W} ight) \langle n | U^{\dagger} | j angle$ $\mathcal{L} = \sum \mathcal{W}^{\dagger} \left(\left(\left. \left| n \right\rangle \left\langle n \right| \mathcal{U}^{\dagger} \left| j \right\rangle \left\langle i \right| \mathcal{U} \left| m \right\rangle \left\langle m \right| \right) \otimes \mathcal{I}^{\overline{\mathcal{A}}} \right) \mathcal{W} ight)$ $W^{\dagger} = W^{\dagger} \Big(\big(\sum |n angle \langle n| \ U^{\dagger} | j angle \langle i | U \ | m angle \langle m| \ \big) \otimes I^{\overline{A}} \Big) W^{\dagger} \Big)$ $W = W^{\dagger} \left(\left(U^{\dagger} \ket{j} \langle i \mid U \right) \otimes I^{\overline{A}} \right) W$ $= W^{\dagger} \Big(\big(U^{\dagger} | j \rangle \langle i | U \big) \otimes \big(V^{\dagger} I^{\overline{A}} V \big) \Big) W$ $W^{\dagger}(U^{\dagger}\otimes V^{\dagger})(\ket{j}\!\!\bra{i}\otimes I^{\overline{A}})(U\otimes V)W^{\overline{A}}$ $=\left[\left(U\otimes V\right)W\right]_{ii}^{A}$

Separation

The evolution matrix of a system *A* can be obtained from the evolution matrix of a system *AB* by a trace operation defined as

$$\left(tr_{B}\left[W\right]^{AB}\right)_{i,j} \stackrel{\text{def}}{=} \sum_{k} \left[W\right]_{(i,k),(j,k)}^{AB}$$

Theorem

$$\left[\boldsymbol{W}\right]^{\boldsymbol{A}} = \operatorname{tr}_{\boldsymbol{B}}\left[\boldsymbol{W}\right]^{\boldsymbol{A}\boldsymbol{B}}.$$

Separation

Proof

$$\begin{pmatrix} \operatorname{tr}_{B} \left[\boldsymbol{W} \right]^{AB} \end{pmatrix}_{i,j} = \sum_{k} \left[\boldsymbol{W} \right]^{AB}_{(i,k),(j,k)}$$

$$= \sum_{k} \boldsymbol{W}^{\dagger} \left(|j\rangle \langle i|^{A} \otimes |k\rangle \langle k|^{B} \otimes I^{\overline{AB}} \right) \boldsymbol{W}$$

$$= \boldsymbol{W}^{\dagger} \left(|j\rangle \langle i|^{A} \otimes I^{B} \otimes I^{\overline{AB}} \right) \boldsymbol{W}$$

$$= \left[\boldsymbol{W} \right]^{A}_{i,j}$$

◆□▶ ◆□▶ ◆ □▶ ◆ □▶ ● □ ● ● ●

Merging

The state of a joint system *AB* can be obtained from the evolution matrices of systems *A* and *B* by the joint product \odot defined as

$$\left(\left[\boldsymbol{W}\right]^{\boldsymbol{A}}\odot\left[\boldsymbol{W}\right]^{\boldsymbol{B}}\right)_{(i,k),(j,l)}\stackrel{\text{def}}{=}\left[\boldsymbol{W}\right]_{i,j}^{\boldsymbol{A}}\left[\boldsymbol{W}\right]_{k,l}^{\boldsymbol{B}}$$

Theorem

$$\left[\boldsymbol{W}\right]^{\boldsymbol{A}\boldsymbol{B}} = \left[\boldsymbol{W}\right]^{\boldsymbol{A}} \odot \left[\boldsymbol{W}\right]^{\boldsymbol{B}}.$$

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

Merging

Proof

$$\begin{pmatrix} \begin{bmatrix} W \end{bmatrix}^{A} \odot \begin{bmatrix} W \end{bmatrix}^{B} \end{pmatrix}_{(i,k),(j,l)}$$

$$= \begin{bmatrix} W \end{bmatrix}^{A}_{i,j} \begin{bmatrix} W \end{bmatrix}^{B}_{k,l}$$

$$= \begin{pmatrix} W^{\dagger} (|j\rangle\langle i|^{A} \otimes I^{B} \otimes I^{\overline{AB}}) W \end{pmatrix} \begin{pmatrix} W^{\dagger} (I^{A} \otimes |I\rangle\langle k|^{B} \otimes I^{\overline{AB}}) W \end{pmatrix}$$

$$= W^{\dagger} (|j\rangle\langle i|^{A} \otimes I^{B} \otimes I^{\overline{AB}}) (I^{A} \otimes |I\rangle\langle k|^{B} \otimes I^{\overline{AB}}) W$$

$$= W^{\dagger} (|j\rangle\langle i|^{A} \otimes |I\rangle\langle k|^{B} \otimes I^{\overline{AB}}) W$$

$$= \begin{bmatrix} W \end{bmatrix}^{AB}_{(i,k),(j,l)}$$

◆□▶ ◆□▶ ◆ □▶ ◆ □▶ ● □ ● ● ● ●

Recovering the Density Matrix

Let $|\psi\rangle$ be a vector in the Hilbert space of the universe. We define $[W]^{A} |\psi\rangle$ by:

$$\left(\left[\boldsymbol{W}\right]^{\boldsymbol{A}}|\psi\rangle\right)_{i,j}\stackrel{\text{def}}{=}\langle\psi|\left[\boldsymbol{W}\right]_{i,j}^{\boldsymbol{A}}|\psi\rangle$$

Theorem

$$\left[\boldsymbol{W}\right]^{\boldsymbol{A}}\left|\psi\right\rangle = \left[\boldsymbol{W}\left|\psi\right\rangle\right]^{\boldsymbol{A}}$$

where

$$\begin{bmatrix} \boldsymbol{W} | \boldsymbol{\psi} \rangle \end{bmatrix}^{\boldsymbol{A}} \stackrel{\text{def}}{=} tr_{\overline{\boldsymbol{A}}} \left(\boldsymbol{W} | \boldsymbol{\psi} \rangle \langle \boldsymbol{\psi} | \boldsymbol{W}^{\dagger} \right) \,.$$

We call $|\psi\rangle$ the *reference vector*.

Recovering the Density Matrix

Proof

$$\begin{split} \left\langle \begin{bmatrix} \boldsymbol{W} \end{bmatrix}^{\boldsymbol{A}} | \psi \rangle \right\rangle_{i,j} &= \langle \psi | \begin{bmatrix} \boldsymbol{W} \end{bmatrix}_{i,j}^{\boldsymbol{A}} | \psi \rangle \\ &= \langle \psi | \left(\boldsymbol{W}^{\dagger} \left(| j \rangle \langle i | \otimes I^{\overline{\boldsymbol{A}}} \right) \boldsymbol{W} \right) | \psi \rangle \\ &= \langle \psi | \left(\boldsymbol{W}^{\dagger} \left(| j \rangle \langle i | \otimes \sum_{k} | \boldsymbol{k} \rangle \langle \boldsymbol{k} | \right) \boldsymbol{W} \right) | \psi \rangle \\ &= \sum_{k} \left(\langle \psi | \boldsymbol{W}^{\dagger} | j \rangle | \boldsymbol{k} \rangle \right) \left(\langle i | \langle \boldsymbol{k} | \boldsymbol{W} | \psi \rangle \right) \\ &= \sum_{k} \langle i | \langle \boldsymbol{k} | \left(\boldsymbol{W} | \psi \rangle \langle \psi | \boldsymbol{W}^{\dagger} \right) | j \rangle | \boldsymbol{k} \rangle \\ &= \left(tr_{\overline{\boldsymbol{A}}} \left(\boldsymbol{W} | \psi \rangle \langle \psi | \boldsymbol{W}^{\dagger} \right) \right)_{i,j} = \left[\boldsymbol{W} | \psi \rangle \right]_{i,j}^{\boldsymbol{A}} \end{split}$$

The proportion of a system A, with evolution Matrix $[W]^A$ in state $|i\rangle$ is given by

$$\left[\boldsymbol{W} \left| \psi \right\rangle \right]_{i,i}$$

where $|\psi\rangle$ is the reference vector.

This proportion is *perceived* as a probability, giving rise to Born's rule!

Separate evolution

Theorem

$$((U \otimes V)[W]^{AB}) = U[W]^{A} \odot V[W]^{B}$$

Proof

$$\begin{pmatrix} (U \otimes V) [W]^{AB} \\ = [(U \otimes V \otimes I)W]^{AB} \\ = [(U \otimes V \otimes I)W]^{A} \odot [(U \otimes V \otimes I)W]^{B} \\ = U[W]^{A} \odot V[W]^{B}$$

And indeed we have



Which means:

$$U([W]^{A}|\psi\rangle) = (U[W]^{A})|\psi\rangle$$

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

Theorem $m{U}ig(ig[m{W}ig]^m{A}ig|\psi
angleig)=ig(m{U}ig[m{W}ig]^m{A}ig)ig|\psi
angle$

Proof

$$U\left(\left[W\right]^{A}|\psi\rangle\right)$$
$$=U\left[W|\psi\rangle\right]^{A}$$
$$=\left[\left(U\otimes I\right)W|\psi\rangle\right]^{A}$$
$$=\left[\left(U\otimes I\right)W\right]^{A}|\psi\rangle$$
$$=\left(U\left[W\right]^{A}\right)|\psi\rangle$$

◆□ > ◆□ > ◆豆 > ◆豆 > ̄豆 _ のへで

As well as



Which means:

$$\operatorname{tr}_{\boldsymbol{B}}\left(\left[\boldsymbol{W}\right]^{\boldsymbol{A}\boldsymbol{B}}|\psi\rangle\right) = \left(\operatorname{tr}_{\boldsymbol{B}}\left[\boldsymbol{W}\right]^{\boldsymbol{A}\boldsymbol{B}}\right)|\psi\rangle$$

◆□ ▶ ◆□ ▶ ◆ □ ▶ ◆ □ ▶ ● □ ● ● ● ●

Theorem $\operatorname{tr}_{B}\left(\left[W\right]^{AB}|\psi\rangle\right) = \left(\operatorname{tr}_{B}\left[W\right]^{AB}\right)|\psi\rangle$

Proof

$$\operatorname{tr}_{B}\left(\left[\boldsymbol{W}\right]^{\boldsymbol{AB}}|\psi\rangle\right)$$
$$=\operatorname{tr}_{B}\left(\left[\boldsymbol{W}|\psi\rangle\right]^{\boldsymbol{AB}}\right)$$
$$=\left[\boldsymbol{W}|\psi\rangle\right]^{\boldsymbol{A}}$$
$$=\left[\boldsymbol{W}\right]^{\boldsymbol{A}}|\psi\rangle$$
$$=\left(\operatorname{tr}_{B}\left[\boldsymbol{W}\right]^{\boldsymbol{AB}}\right)|\psi\rangle$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへぐ

Introduction

Intuitive Desiderata

Local States

Local Evolution

Observations in Quantum Mechanics

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

Parallel Lives vs Many Worlds

A Local Realist Formalism

Conclusion

Conclusion

Our work improves on Everettian axioms in the following ways:

The universal wave function cannot be the complete description of reality AND be local.

(ロ) (同) (三) (三) (三) (三) (○) (○)

 Our system of axioms is simple, local, realistic, deterministic and complete.

References

- D. Deutsch and P. Hayden, "Information flow in entangled quantum systems", *Proceedings of the Royal Society of London* A456(1999):1759–1774, 2000.
- G. Brassard and P. Raymond-Robichaud, "Can free will emerge from determinism in quantum theory?", in *Is Science Compatible* with Free Will? Exploring Free Will and Consciousness in the Light of Quantum Physics and Neuroscience, A. Suarez and P. Adams (editors), Springer, pp. 41–61, 2013.



"About your cat, Mr. Schrödinger—I have good news and bad news."